

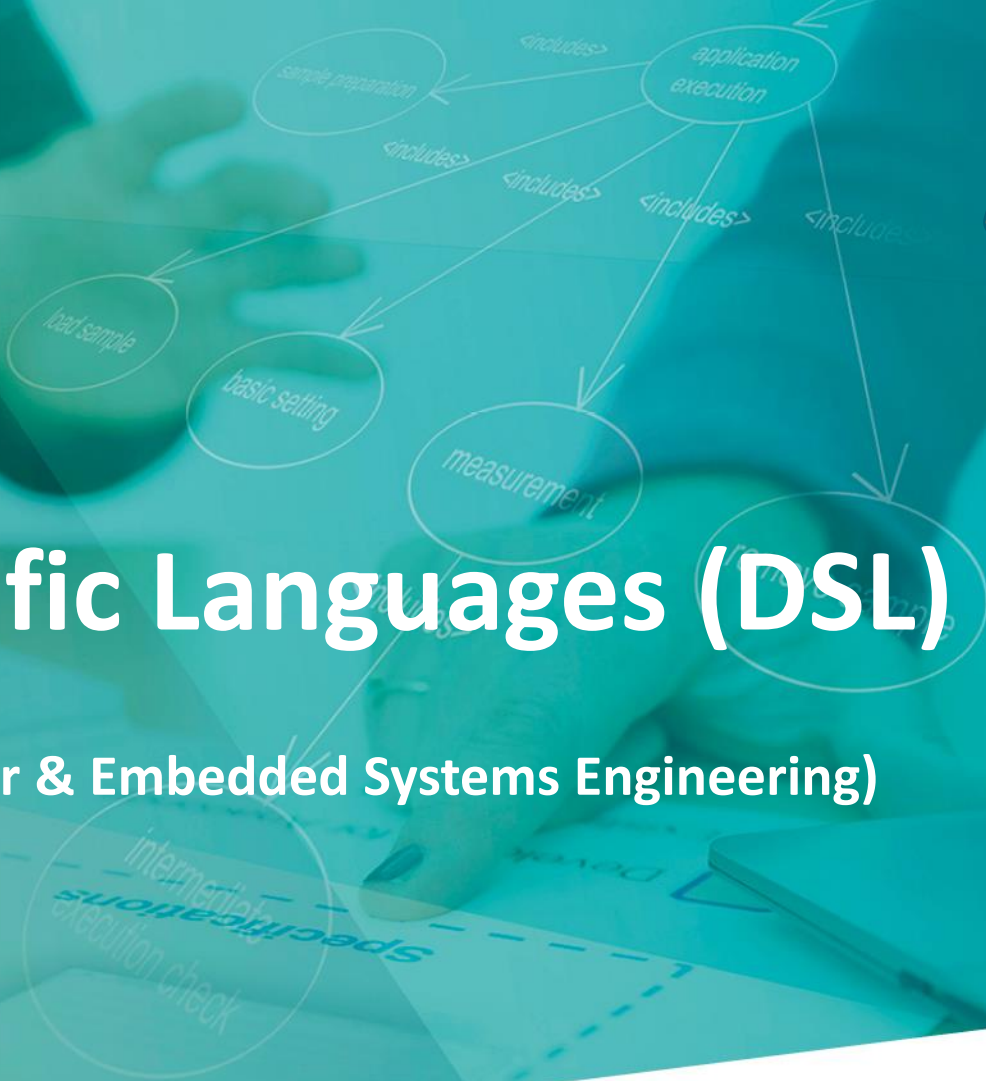
# Domain-Specific Languages (DSL)

Software Systems (Computer & Embedded Systems Engineering)

Arjan Mooij

January 2023 (week 8)

Based on the DSL awareness training of ESI.



# Objectives

## At the end of the course, you should be able to:

- Explain the purpose of Domain-Specific Languages, including several application areas
- Explain the basics of grammars and parsing
- Create basic textual Domain-Specific Languages, including editor support, validation and generators

## Assessment:

- Modeling assignment using Domain-Specific Languages (in groups of 2 students)
- Reflection document on Model-Based Development (individual)

# Motivation

## Domain-Specific Languages (DSL)

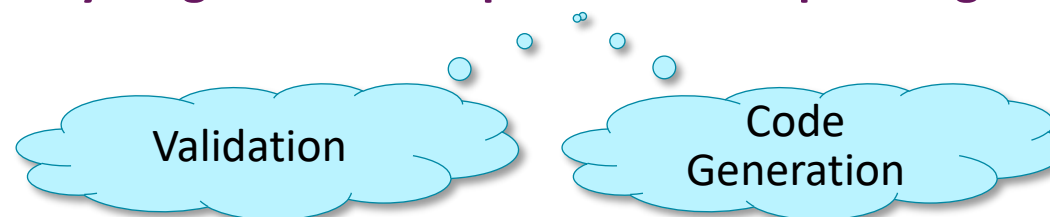
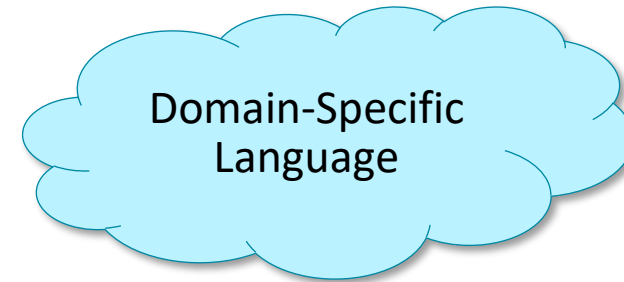
# What is Jargon?

## Oxford dictionaries:

- **Special words or expressions**
  - used by a profession or group
  - that are difficult for others to understand

## Wikipedia:

- **Terminology defined in relationship to a specific activity, profession, group, or event**
    - ... a barrier to communication with those not familiar with the language
- **A standard term may be given a more precise or unique usage**



# What is a Domain-Specific Language?

- What are your associations with the term Domain-Specific Language?
- Do you know any Domain-Specific Languages?

Think → Pair → Share

# What is a Domain-Specific Language?

## General-purpose programming languages:

- C, C++, Java, Python, etc.

## Horizontal

- HTML
- SQL

## Domain-specific languages:

- for web pages
- for relational database queries

## Vertical

## Domain-specific languages:

- Specifically designed for a specific application by a single company

```
#include <stdio.h>

int main(void)
{
    printf("hello, world\n");
}
```

```
<!DOCTYPE html>
<html>
  <head>
    <title>Hello HTML</title>
  </head>
  <body>
    <p>Hello World!</p>
  </body>
</html>
```

```
SELECT *
FROM Book
WHERE price > 100
ORDER BY title;
```

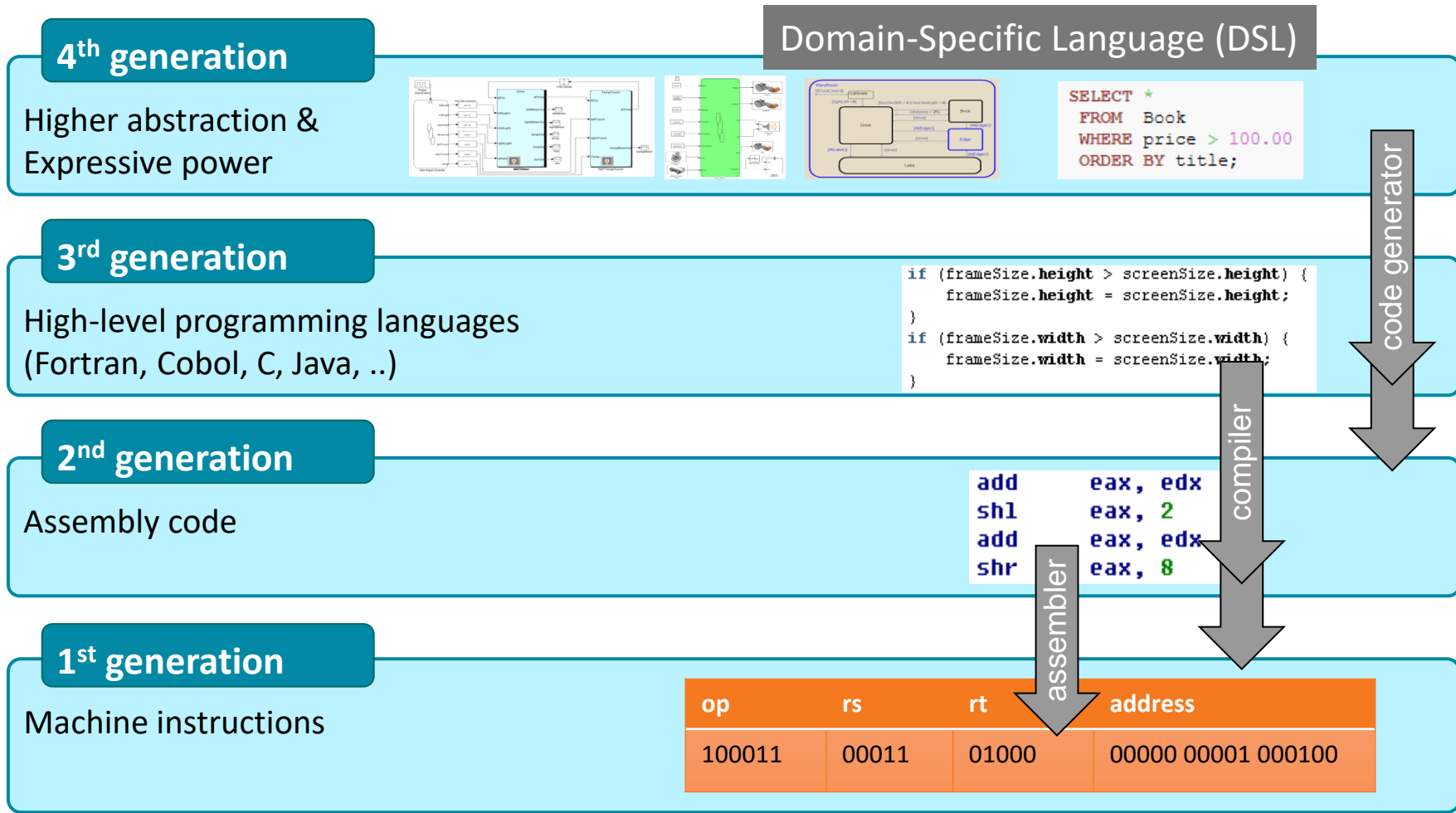
**Canon** **ASML** **VANDERLANDE** **PHILIPS** **THALES**

# What about the other model-based techniques from this course?

- **PlantUML** for **Unified Modeling Language (UML)**
- **YAKINDU Statechart Tools** for **Finite-State Machines (FSM)**

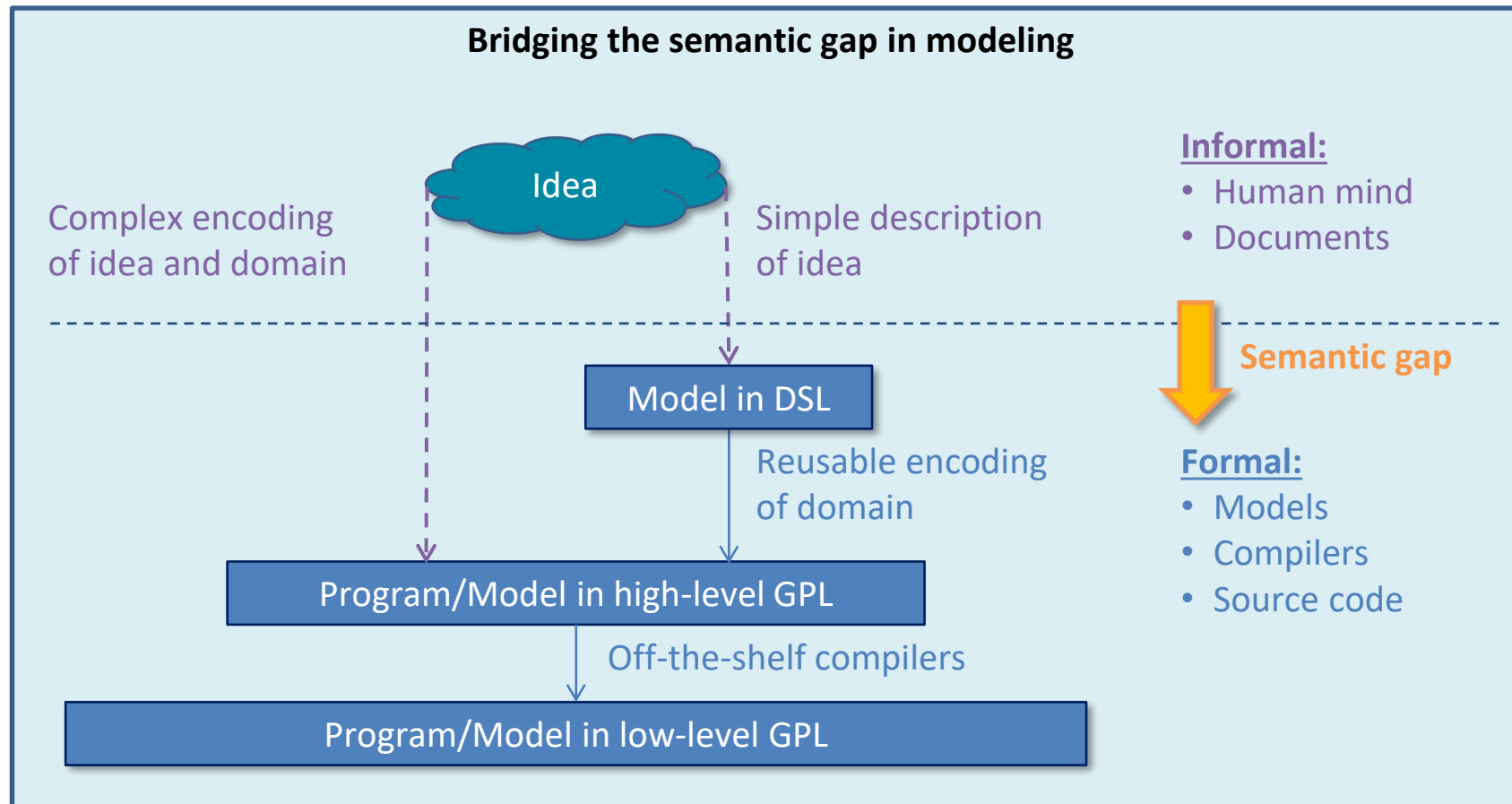
➔ **Horizontal DSLs**

# Generations of programming languages





# Modeling Perspective on DSLs



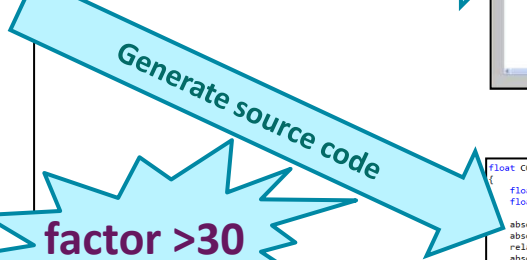
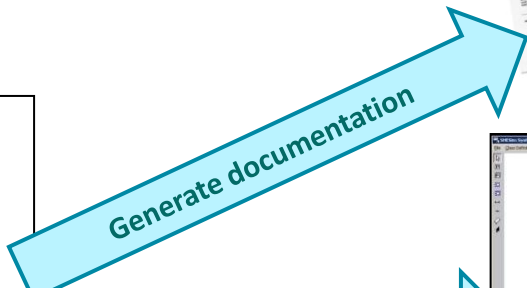
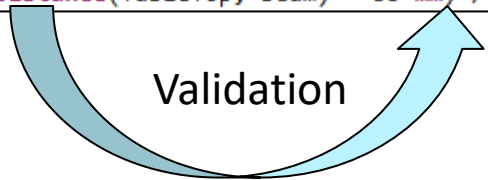


# DSL as Central Artifact

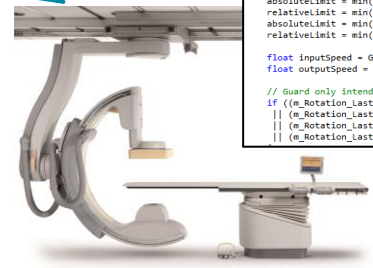
```

restriction VeryCloseTableTopAndBeam
  activation
    Distance(TableTop, Beam) < 20 mm
  effects
    userGuidance "TableTop and Beam very close"
    relative limit TableTop*[Rotation, Translation],
      Beam*[Rotation, Translation]
    at 0

restriction ApproachingTableTopAndBeam
  activation
    Distance(TableTop, Beam) < 35 mm + 15 cm
  effects
    userGuidance "TableTop and Beam approaching"
    relative limit TableTop*[Rotation, Translation],
      Beam*[Rotation, Translation]
    at (Distance(TableTop, Beam) - 35 mm) / 15 cm
  
```



**factor >30**



```

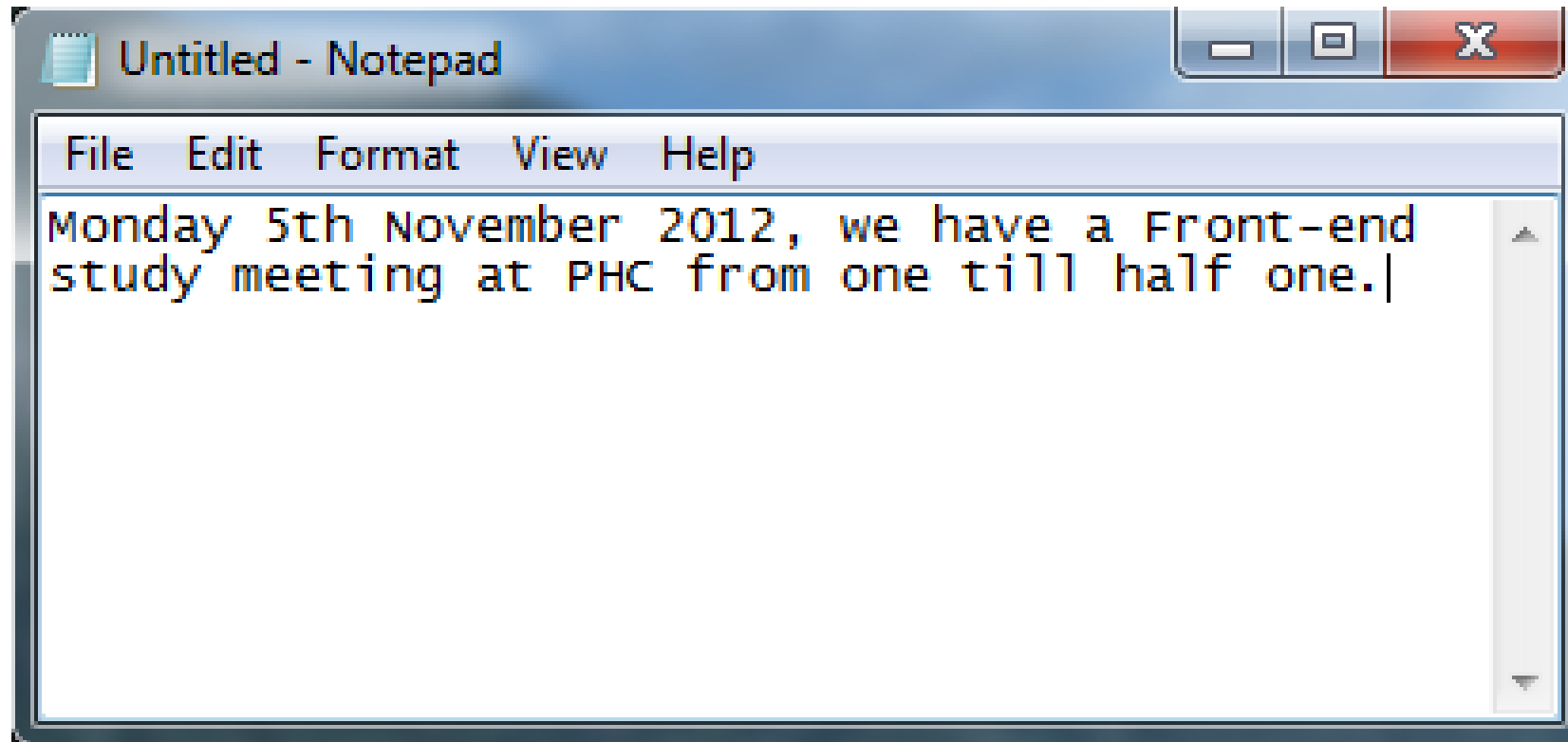
Float CObject_Beam::GetRotationScaling()
{
  float absoluteLimit = GEH_t_float_max;
  float relativeLimit = 1;

  absoluteLimit = min(absoluteLimit, m_Rotation_AbsoluteLimit_DetectorRotationInBetween);
  absoluteLimit = min(absoluteLimit, m_Rotation_AbsoluteLimit_VeryCloseTableTopAndBeam);
  relativeLimit = min(relativeLimit, m_Rotation_RelativeLimit_ApproachingTableTopAndBeam);
  absoluteLimit = min(absoluteLimit, m_Rotation_AbsoluteLimit_VeryCloseTableTopAndDetector);
  relativeLimit = min(relativeLimit, m_Rotation_RelativeLimit_ApproachingTableTopAndDetector);
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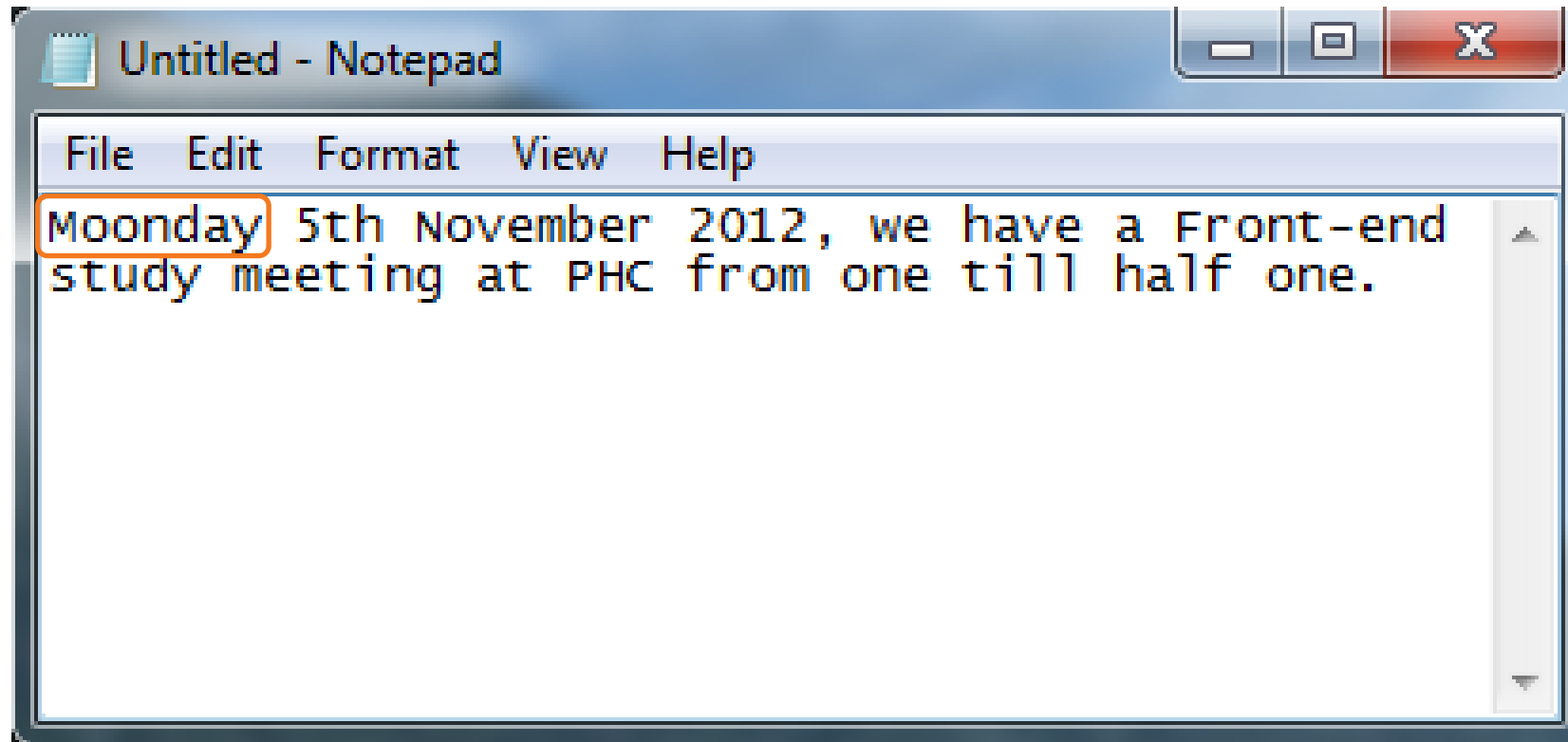
  float inputSpeed = GetRequestedRotSpeed();
  float outputSpeed = min(inputSpeed * relativeLimit, absoluteLimit);

  // Guard only intended to reduce calls to logging
  if ((m_Rotation_LastAbsoluteLimit != absoluteLimit) ||
      (m_Rotation_LastRelativeLimit != relativeLimit) ||
      (m_Rotation_LastInputSpeed != inputSpeed) ||
      (m_Rotation_LastOutputSpeed != outputSpeed))
  
```

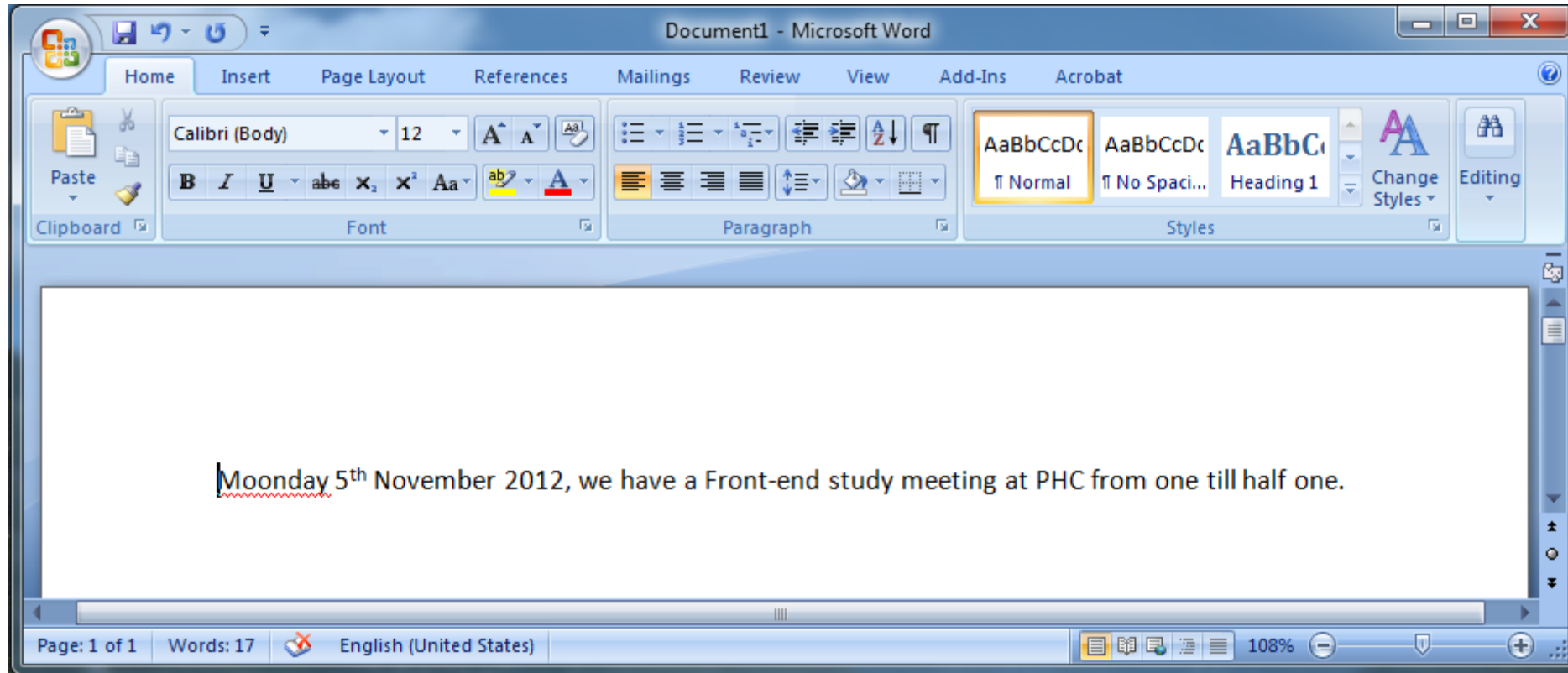
## Microsoft Notepad: A Correct Sentence



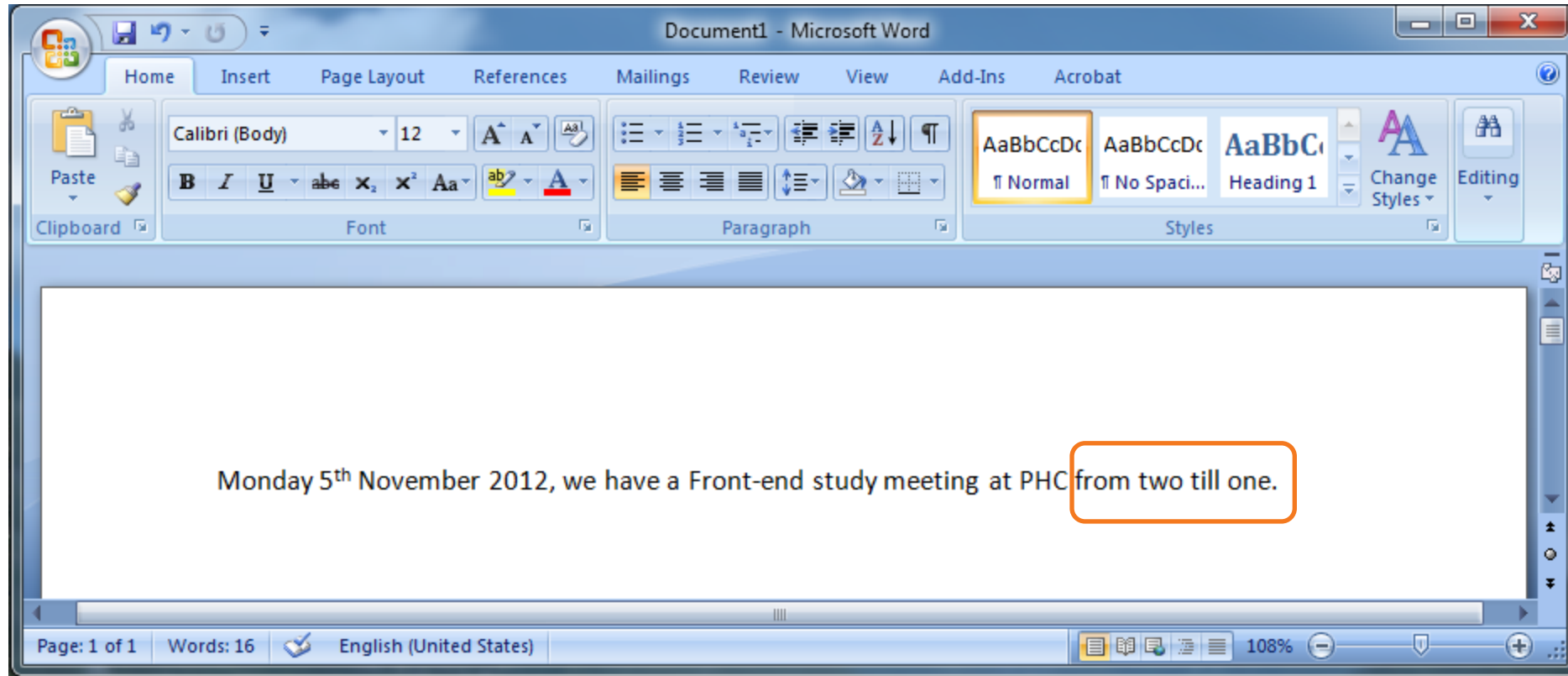
## Microsoft Notepad: No Problem Detected, but ...



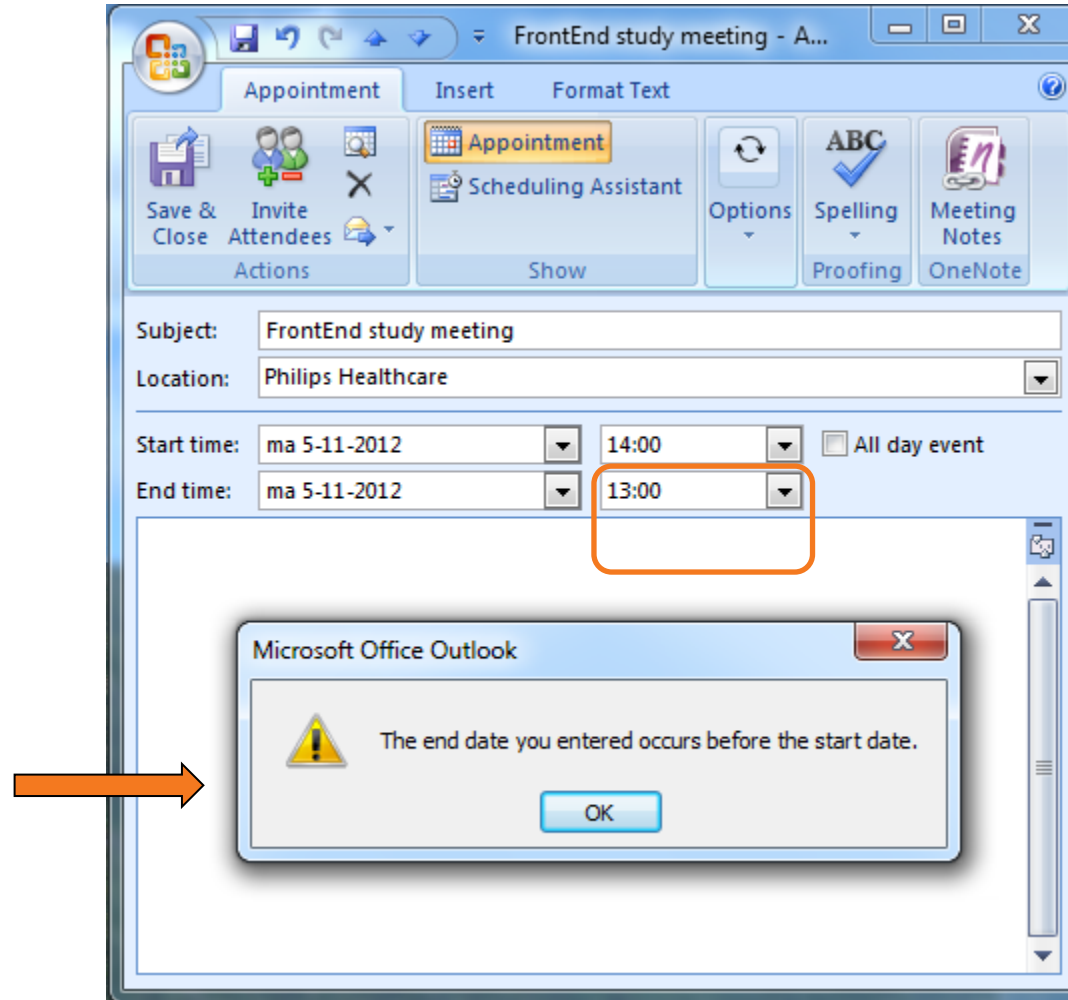
# Microsoft Word: Spelling Error



## Microsoft Word: No Problem Detected, but ...



# Microsoft Outlook: Wrong Times





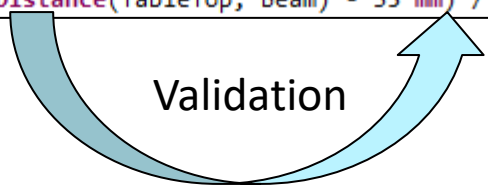
# DSL as Central Artifact

```

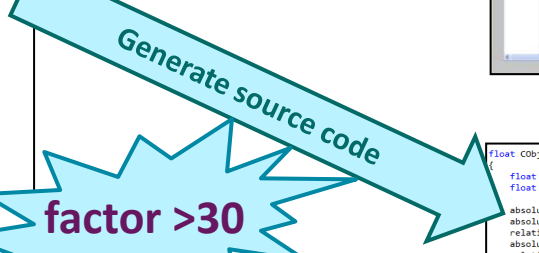
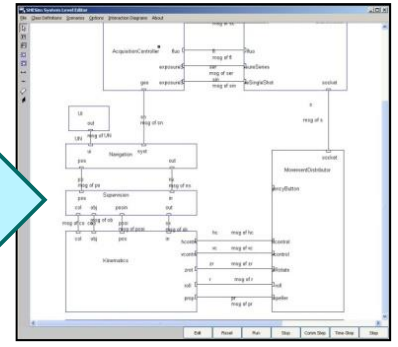
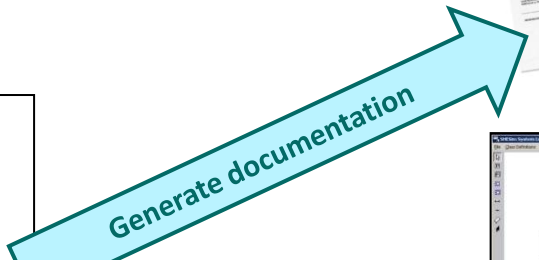
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    at (Distance(TableTop, Beam) - 35 mm) / 15 cm
  
```

Xtext  
Xtend



**factor >30**



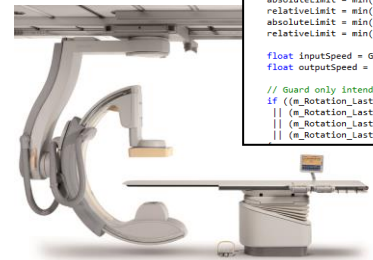
```

float Object_Beam::GetRotationScaling()
{
  float absoluteLimit = GEN_t_float_max;
  float relativeLimit = 1.;

  absoluteLimit = min(absoluteLimit, m_Rotation_AbsoluteLimit_DetectorRotationInBetween);
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      (m_Rotation_LastOutputSpeed != outputSpeed))
  
```

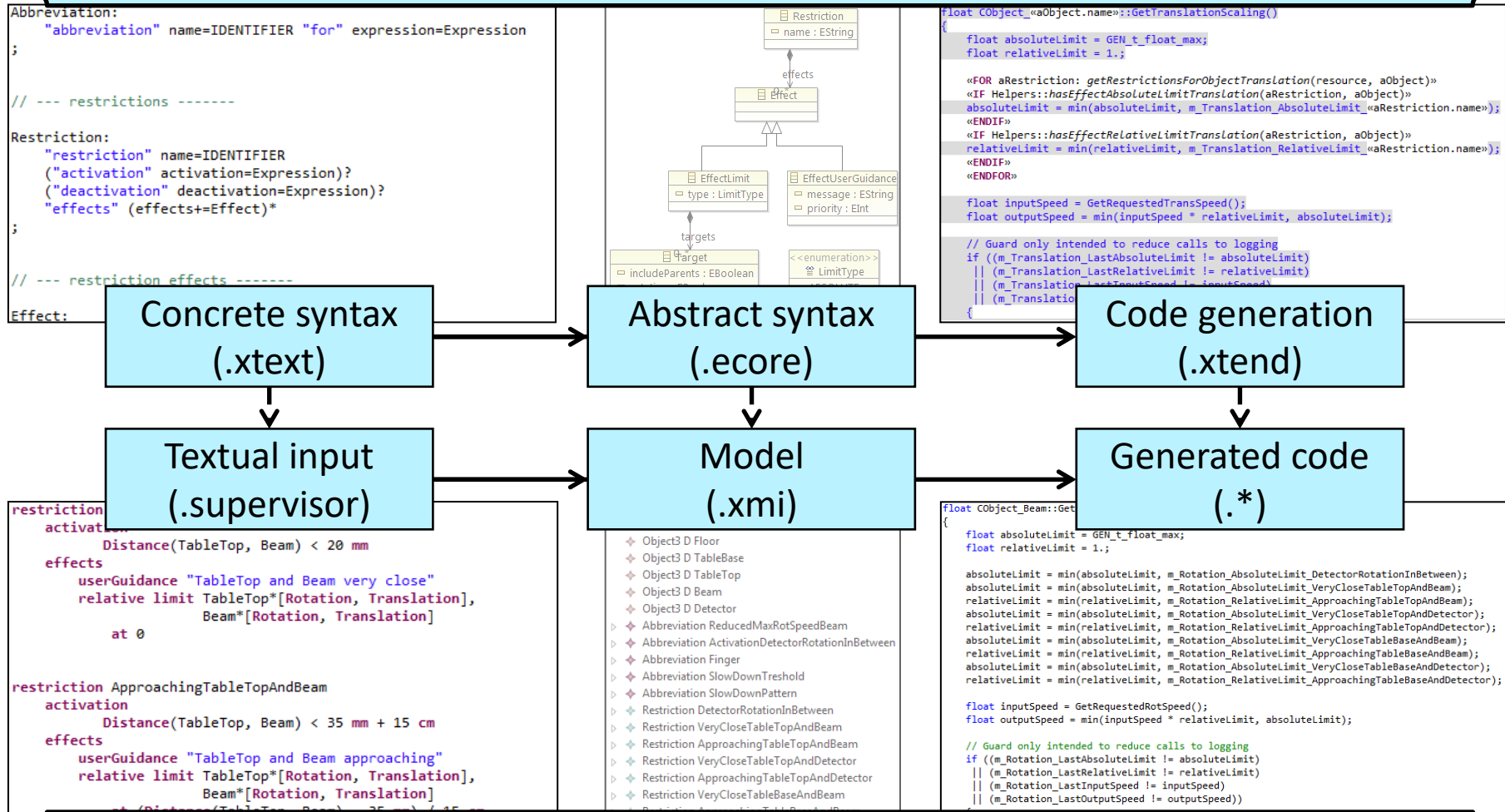




# Metamodels and grammars

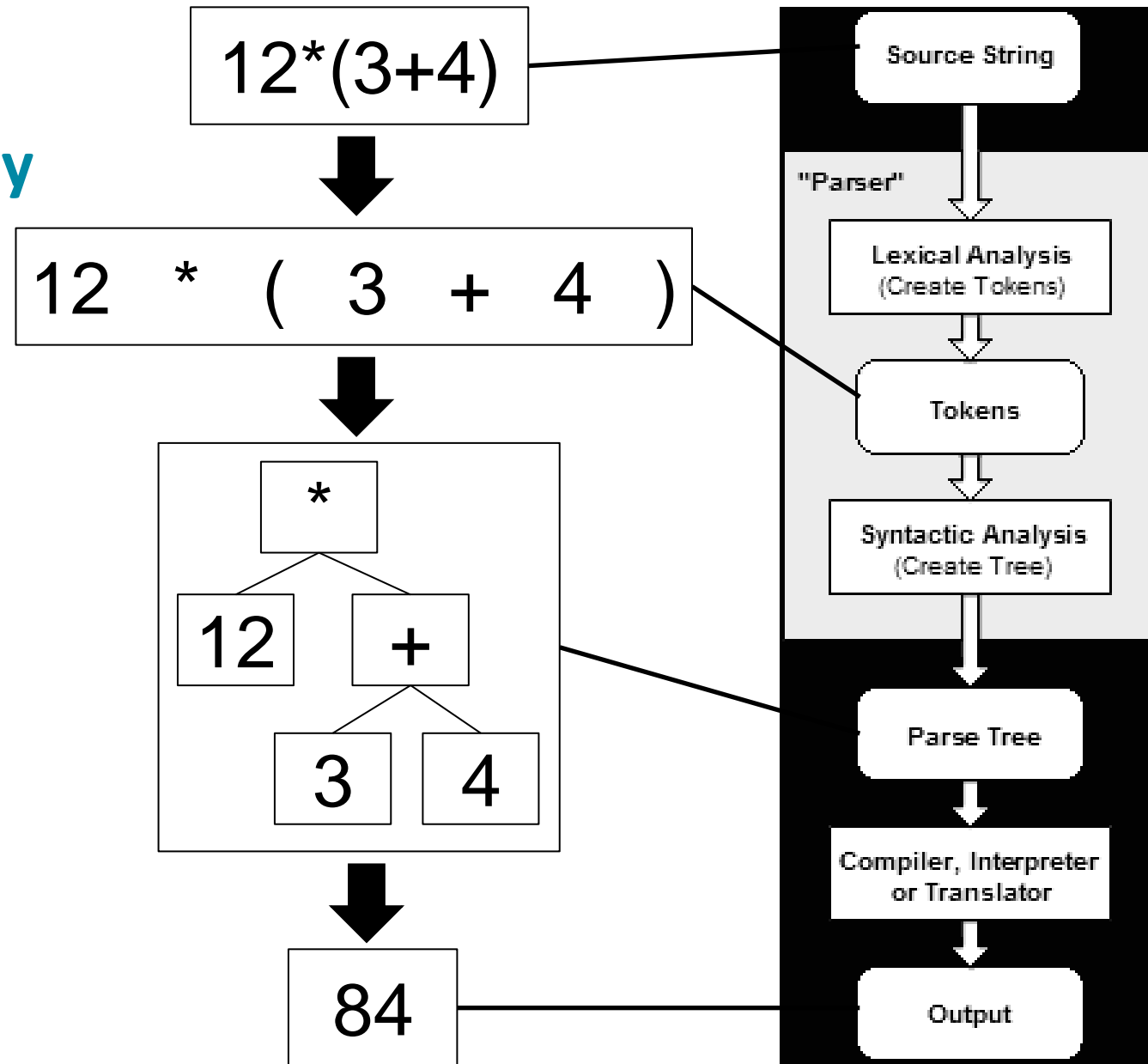
## Domain-Specific Languages (DSL)

## Meta level, for developing the general infrastructure

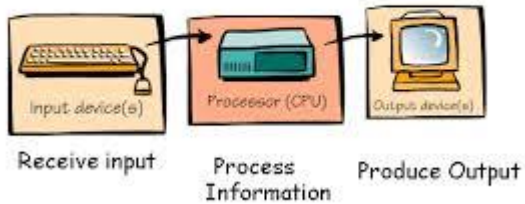


## Instance level, for developing a specific system

# Compiler Technology



## What Computers Do



# Lexical Analysis

	choice
?	optional
*	zero or more times
+	one or more times

- Regular expressions using Extended Backus-Naur Form (EBNF)

- Literal character sequences

'while'

'('

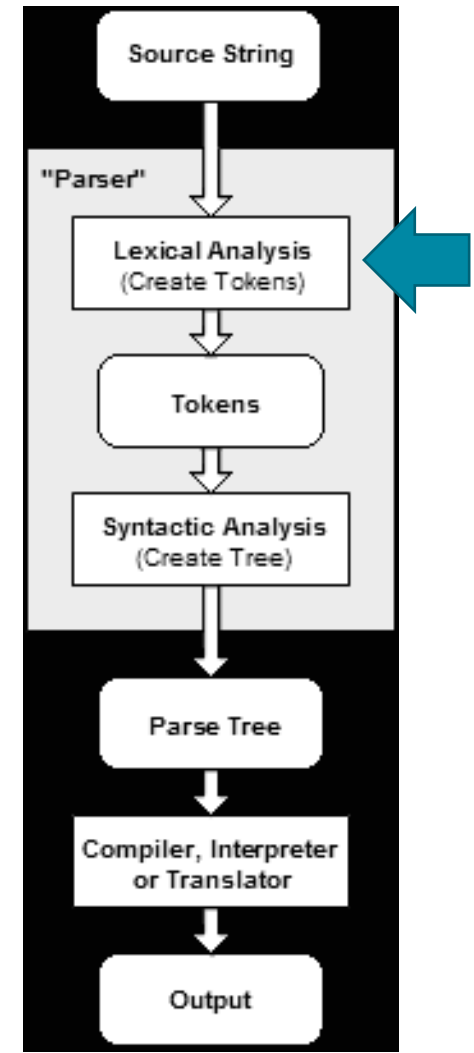
- Custom terminal definitions

```
terminal INT: ('0'..'9')+;
```

```
terminal ID: '^?'('a'..'z'|'A'..'Z'|'_'|'0'..'9')*;
```

- Terminals that are imported by default in Xtext:

- ID
- INT
- STRING
- ML\_COMMENT (= multi-line comment) ← Hidden by default
- SL\_COMMENT (= single-line comment) ← Hidden by default
- WS (= whitespace, tab, newline) ← Hidden by default



# Syntactic Analysis

	choice
?	optional
*	zero or more times
+	one or more times

## Context-free grammars in terms of tokens

- More expressive than regular expressions, e.g., recursion to parse nested brackets

```
Task name AvoidBorder Task freq 100
```

```
Task moves
```

```
Move name Turn Start border End noBorder Speed 15 Rotation 90
```

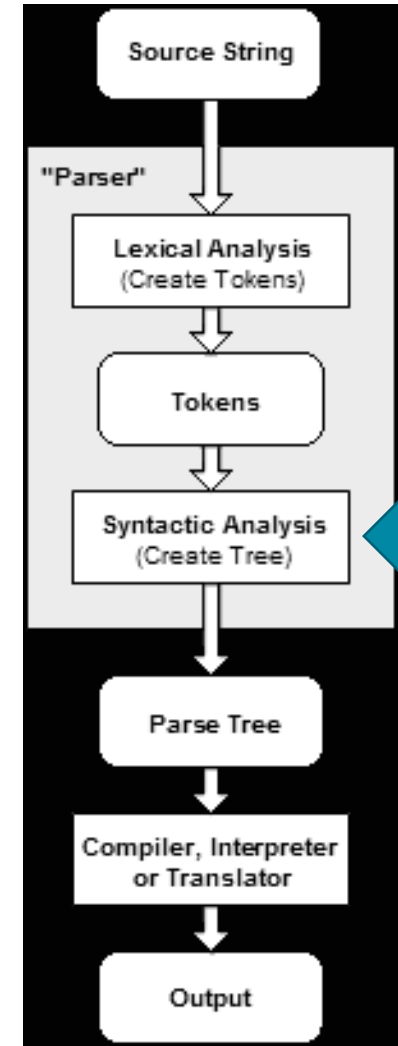
```
Move name Back Speed 30
```

Robot: (Message | Task)\*

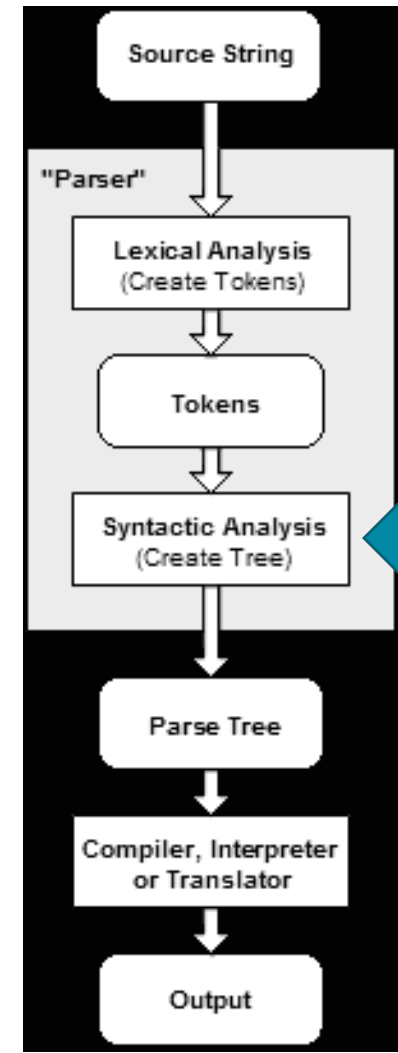
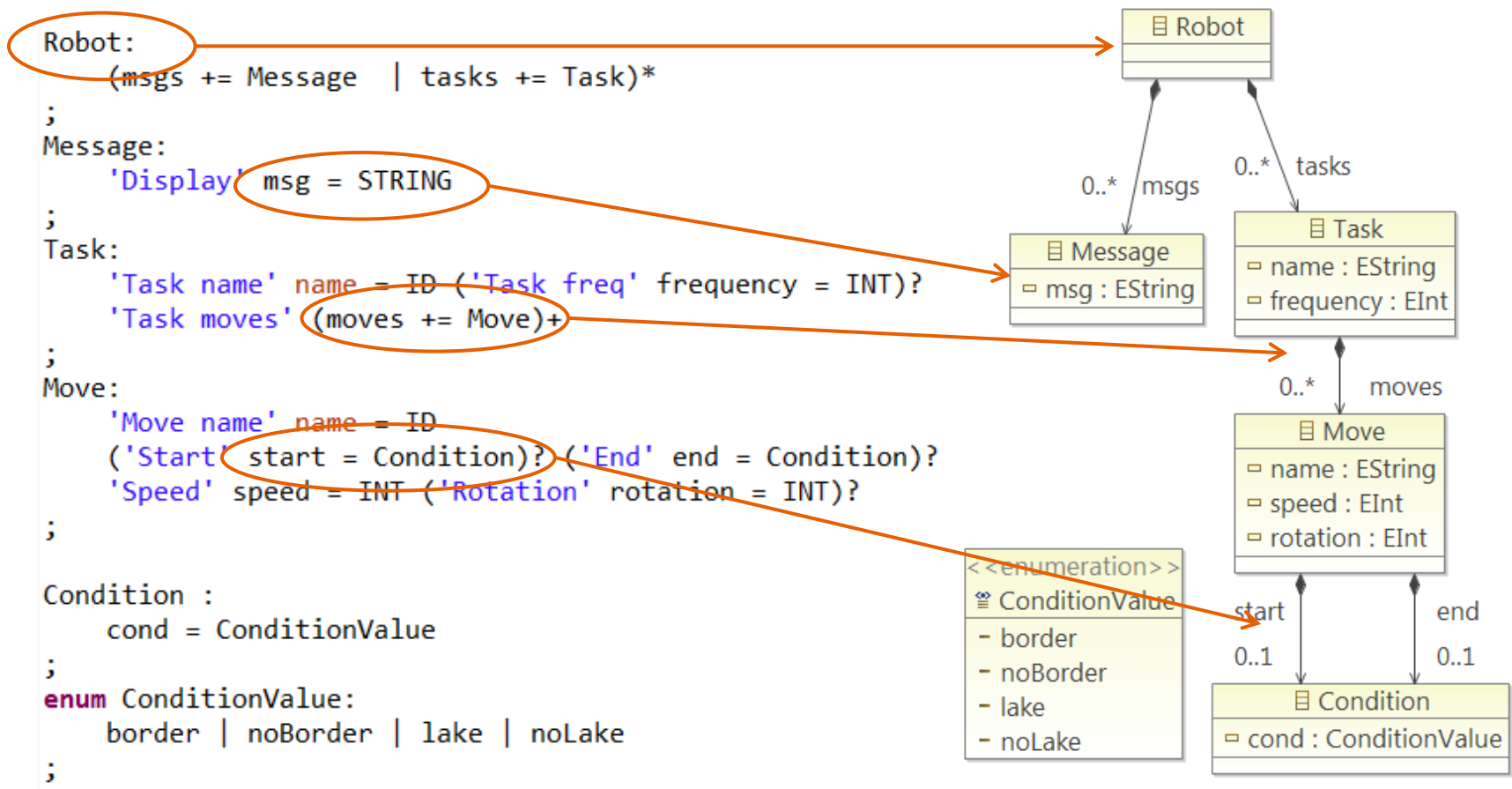
Message: 'Display' STRING

Task: 'Task' 'name' ID ('Task' 'freq' INT)?  
'Task' 'moves' (Move)+

Move: 'Move' 'name' ID  
( 'Start' Condition)? ('End' Condition)?  
'Speed' INT ('Rotation' INT)?



# Abstract Syntax



# Concrete and Abstract Syntax

```

StateMachine:
  'StateMachine' name = ID
  'Init' init = [State]
  'States' states += State+
  'Events' events += Event+
  'Transitions'
  transitions += Transition*
  'Final' final += [State];
  
```

```

State: name=ID;
Event: name =ID;
  
```

```

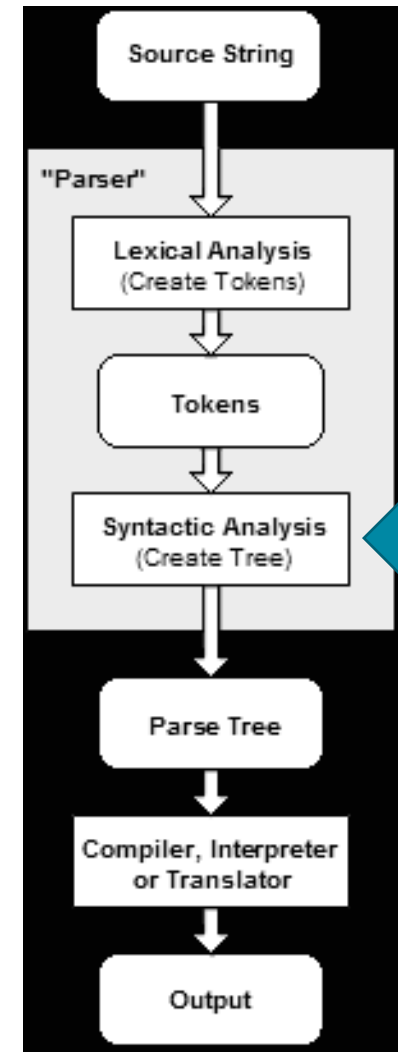
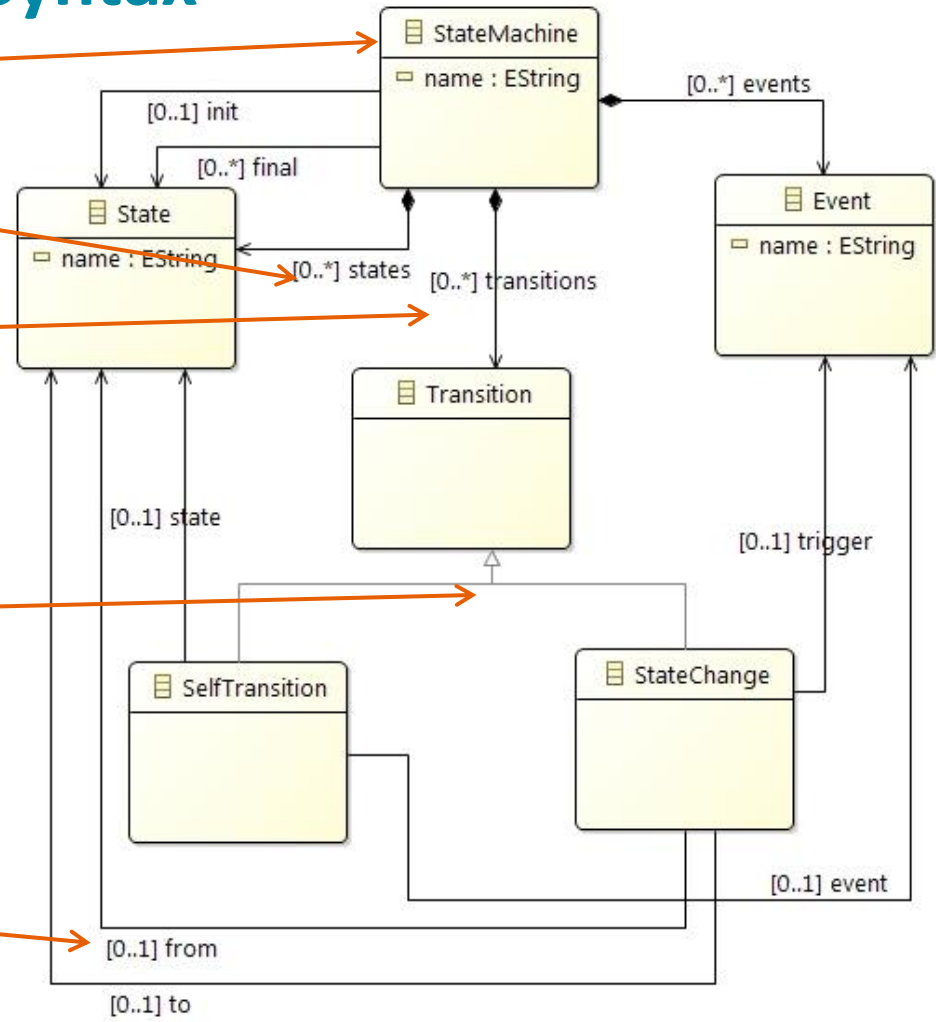
Transition:
  SelfTransition | StateChange;
  
```

```

SelfTransition:
  'FromTo' state = [State]
  'Event' event = [Event]
  ;
  
```

```

StateChange:
  'From' from = [State]
  'Trigger' trigger = [Event]
  'To' to = [State];
  
```



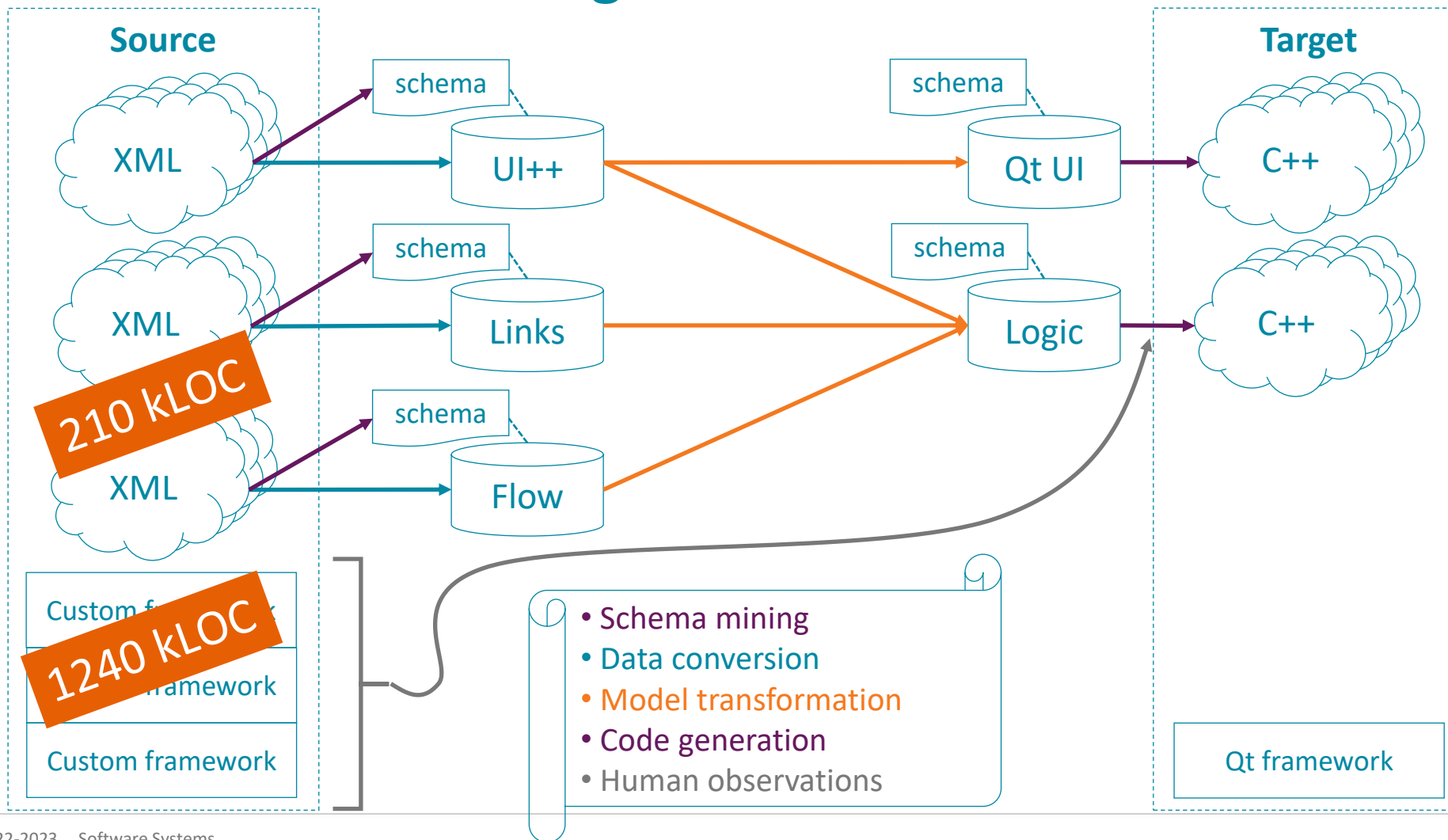
# Field-service procedures at Philips IGT

## Domain-Specific Languages (DSL)



# Application:

# Migration



# Application: Model extraction

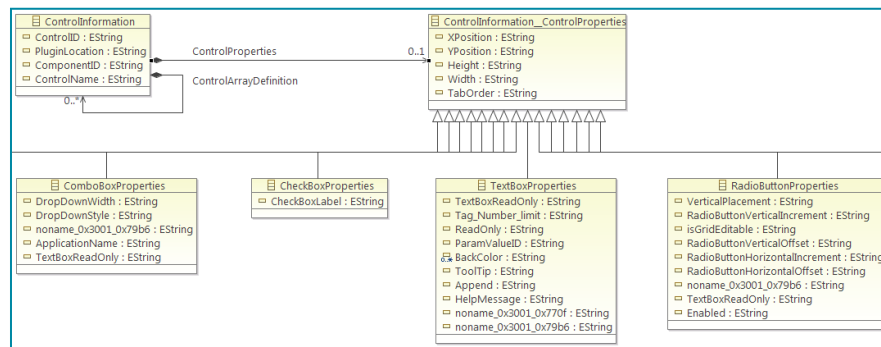
```

<DataObject ObjectType="PanelProperties">
  <Attribute Group="0x3001" Element="0x652c" PMSVR="IInt16">5</Attribute>
  <Attribute Name="XPosition" Group="0x3001" Element="0x7600" PMSVR="IInt16">0</Attribute>
  <Attribute Name="YPosition" Group="0x3001" Element="0x7601" PMSVR="IInt16">145</Attribute>
  <Attribute Name="Height" Group="0x3001" Element="0x7602" PMSVR="IInt16">35</Attribute>
  <Attribute Name="Width" Group="0x3001" Element="0x7603" PMSVR="IInt16">60</Attribute>
  <Attribute Name="TabOrder" Group="0x3001" Element="0x7609" PMSVR="IInt16">2</Attribute>
  <Attribute Name="LayerType" Group="0x3001" Element="0x77d1" PMSVR="IString">"Data"</Attribute>
</DataObject>
    
```

XML data



Schema



Converted data

```

ControlProperties = PanelProperties {
  Dock = 5
  XPosition = 0
  YPosition = 145
  Height = 35
  Width = 60
  TabOrder = 2
  LayerType = "Data"
}
    
```

# Application:

# Code generation

```
// --- node FULLAUTO (stage FullAutomatic) -----
node
  name = "FULLAUTO"
  transitions
    OK -> "STATIC"
    Cancel -> "FINALIZATION"
  stage = FullAutomatic
  part = ""
  UIResource
    assembly = "FSCGeneratorUIDefinitions"
    id = "FSCXGNTubeAdaptationAdjustmentFullAutoUIDef"
  mapping
    event id 21: element "C24"
    event id 20: element "C25"
    event id 10: element "C33" ScrollToLatest
    event id 22: element "C23"
    event id 23: element "ProgressBarCtrl" conversion "TubeLoadPowerFactorToStyleSheet"
    event id 11: element "C31"
    event id 100: element "C9" Append
    event name "ExecutionBegun": element "C35_ProcedureEvents"
    event name "PartCompleted": element "C35_ProcedureEvents"
```

```
#include "stdafx.h"
#include "«fileName».h"

#include <QDoubleValidator>
#include <QMessageBox>

#include "Utility.h"

«FOR node : procedure.nodesUI»
«FOR mapping : node.mappingsId»
const ULONG «constant(node, mapping)» = «mapping.id»L;
«ENDFOR»
«FOR mapping : node.mappingsIdEvent»
const ULONG «constant(node, mapping)» = «mapping.id»L;
«ENDFOR»
«FOR action: node.actionsId»
const ULONG «constant(node, action)» = «action.id»L;
«ENDFOR»

«fileName»: «fileName»(QString qstrProcedureName, CLSID component, QWidget *parent, bool bStubbed)
: «NewFlowGeneratorHeader::parentClass(procedure)»(qstrProcedureName, component, parent, bStubbed)
«FOR node : procedure.nodesUI»
, m_qwidget_node«node.name»(NULL)
«ENDFOR»
```

DSL model

Template



Generated code

```
#include "stdafx.h"
#include "FlowFSCXGNTubeAdaptationAdjustment.h"

#include <QDoubleValidator>
#include <QMessageBox>

#include "Utility.h"

const ULONG FlowFSCXGNTubeAdaptationAdjustment_Preset_getset_C46 = 1L;
const ULONG FlowFSCXGNTubeAdaptationAdjustment_FULLAUTO_event_C24 = 21L;
const ULONG FlowFSCXGNTubeAdaptationAdjustment_FULLAUTO_event_C25 = 20L;
const ULONG FlowFSCXGNTubeAdaptationAdjustment_FULLAUTO_event_C33 = 10L;
const ULONG FlowFSCXGNTubeAdaptationAdjustment_FULLAUTO_event_C23 = 22L;
const ULONG FlowFSCXGNTubeAdaptationAdjustment_FULLAUTO_event_ProgressBarCtrl = 23L;
const ULONG FlowFSCXGNTubeAdaptationAdjustment_FULLAUTO_event_C31 = 11L;
const ULONG FlowFSCXGNTubeAdaptationAdjustment_FULLAUTO_event_C9 = 100L;

FlowFSCXGNTubeAdaptationAdjustment::FlowFSCXGNTubeAdaptationAdjustment(QString qstrProcedureName, CLSID component, QWidget *parent, bool bStubbed)
: BaseAdjustment(qstrProcedureName, component, parent, bStubbed)
, m_qwidget_nodePreset(NULL)
, m_qwidget_nodeFULLAUTO(NULL)
, m_qwidget_nodeSTATIC(NULL)
```





# Conclusion: It pays off!

## Main challenges:

- Extract the domain knowledge from the legacy software
- Avoid that the rejuvenated software resembles the legacy too much

## Industrial results:

- Redesigned software: 20 times smaller code base than legacy software
- Model-based migration: 6 times less effort than manual

More time for innovation!



Dirk Jan Swagerman



Gernot Eggen



Hans van Wezep



Martien van der Meij



Aron van Beurden

**PHILIPS**

Embedded Systems Innovation **BY TNO**



Arjan Mooij



Jozef Hooman

# Closing remarks

## Domain-Specific Languages (DSL)

## General Tips and Tricks

- It may help to first create an example instance, and afterwards create a grammar.
  - “test-driven”
- Look at the abstract syntax!
  - E.g., check missing attribute names
- Don't be too restrictive in the grammar; validation can be used for extra checks.
- Focus on specification (not on execution)
- A DSL is not a general-purpose programming language
- Use enumeration types when appropriate:

```
enum ChangeKind :  
    ADD      = 'add'  
    | MOVE   = 'move'  
;
```

# Closing remarks

- **Lab session work:**
  - Follow the manual “Creating a Domain Specific Language (DSL) with Xtext” up to section 3.5
    - [http://www.cs.ru.nl/J.Hooman/DSL/Creating a Domain Specific Language \(DSL\) with Xtext.pdf](http://www.cs.ru.nl/J.Hooman/DSL/Creating_a_Domain_Specific_Language_(DSL)_with_Xtext.pdf)
  - Modeling assignment
    - Create an Xtext grammar (+ some example instances)
    - Create validation and code generators